

# Rviz

ROS1

## MARKER SETTING

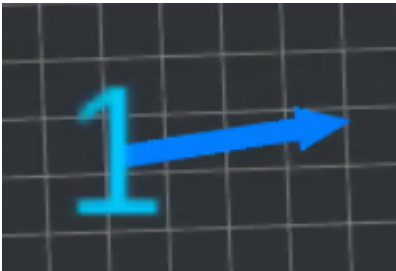
Set marker scale on map

1.00

SET

1.0

set



marker

## ADD GOAL

Tips:use 2D Nav Goal first,then adjust param below

Maximum goal distance for auto insert goal(m):

10.0

X(m):

-3.185

Y(m):

-3.190

R(°):

52.262

GOTO

ADD GOAL TO LIST

## 2D Nav Goal

DELETE ALL GOAL

MODE

☐ CYCLE MODE

☐ SEQUENCE MODE

☒ STEP MODE

Goal tolerance for cycle and sequence mode (m)

2.000

cycle mode	
sequence mode	
step mode	

Goal tolerance

CONTROLLER

☐ REVERSE

NEXT GOAL:

START/CONTINUE

STOP

- REVERSE
- START STOP NEXT GOAL