Quick Start Guide

The steps to follow for the first-time use of the device：

1. Download and refer to the [product user manual and simplified model](), especially the remote control section.
2. Lift the chassis up to ensure that all wheels are off the ground.
3. Turn on the chassis power. If you hear four consecutive beeps indicating a successful startup, check if the battery level display is ok.
4. If you have a remote controller, switch it to the CAN mode. For instructions on how to switch modes, please refer to the [product user manual]().
5. Slowly push the remote controller joystick and observe if the motion is right.
6. Turn off the power, connect the CAN and power lines properly, please refer to [Standard CAN Extended Interface]() and [CAN bus configuration]().
7. Users who use ROS please install the ROS package, please refer to the [ROS-SDK]().
8. Please refer to the [ROS-demo]() for using demos with ROS.
9. If there are testing requirements, you can download the [XVIEW testing system]().
10. For users who directly use CAN or USB control, please refer to the [standard CAN protocol]() first, and use XVIEW or a CAN analyzer in conjunction with it.